

# MEI Structured Mathematics

## Module Summary Sheets

# **Mechanics 2** (Version B: reference to new book)

Topic 1: Force

A Model for Friction

Moments of Force

Freely pin-jointed light frameworks

- Topic 2: Work, Energy, Power
- Topic 3: Momentum and Impulse
- Topic 4: Centre of Mass
- Topic 5: Using Experimental Results

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References:	Coulomb's Laws	E.g. a block is placed on a rough surface where $\mu = 0.8$ .
Example 1.1 Pages 4-5	<ol> <li>Friction opposes relative motion between two surfaces in contact.</li> <li>Friction is independent of the relative speed of the surfaces.</li> </ol>	(1) The surface is flat. There are no horizontal forces acting and so there will be no friction. $M_g N$
Exercise 1A Q. 4 Example 1.2 Page 5	<ol> <li>The magnitude of the frictional force has a maximum value which depends on the normal reaction between the surfaces and the roughness of the surfaces in contact.</li> <li>If there is no sliding between the surfaces F ≤ μR where F is the frictional force and R is the normal reaction. μ is called the coefficient of friction.</li> <li>When sliding is about to occur,</li> </ol>	(2) The surface is a slope of angle 20 <sup>0</sup> . Resolving perpendicular to the slope: $R = 10g\cos 20 = 92.1$ The maximum value of <i>F</i> is $\mu R$ $F = 92.1 \times 0.8 = 73.7$ (3 s.f.). The component of weight down the slope is $10g\sin 20 = 33.5$ Since $33.5 < 73.7$ , there will be no motion and so F = 33.5 (3 s. f.).
Page 5 Exercise 1A Q. 2	<ol> <li>when sharing is about to occur, friction is said to be limiting and F = μR.</li> <li>When sliding occurs F = μR.</li> <li>For any pair of surfaces, μ is constant.</li> </ol>	(3) The slope is $\theta^0$ such that sliding is about to occur. Find $\theta^0$ . As before: $R = 10g\cos\theta$ No motion along slope means that $10g\sin\theta = F$ As sliding is about to occur, $F = \mu R$ $\theta^0$ R N F N 10g N
References: Chapter 1 Pages 4-8 Example 1.3 Page 6 Exercise 1A Q. 8, 9	Modelling with friction It is often satisfactory to model a situation as having negligible friction. We then describe the surfaces as 'smooth'. Otherwise the surfaces are described as 'rough'. Note that 'smooth' surface and a 'smooth' curve are not the same thing.	$\Rightarrow 10g \sin \theta = \mu 10g \cos \theta$ $\Rightarrow \tan \theta = 0.8$ $\Rightarrow \theta = 38.7^{0}.(3 \text{ s. f.}).$ (4) The slope is 40 <sup>0</sup> . Find the acceleration. (4) The slope is 40 <sup>0</sup> . Find the acceleration. (4) Maximum $F = \mu R$ $= 0.8 \times 10g \cos 40 = 8g \cos 40.$ So applying Newton's 2nd law
Mechanics 2 Version B: page 2 Competence states © MEI	ments d 1, 2, 3, 4	So applying Newton's 2nd law $10g \sin 40 - 8g \cos 40 = 10a$ $\Rightarrow 10a = 63.0 - 60.1 = 2.9$ $\Rightarrow$ acceleration is 0.29 m s <sup>-2</sup> (2 s.f.) $a = 0$ and $F \neq \mu R$ ; $F = 10g \sin \theta$





References: Chapter 3 Pages 25-27	<b>Rigid bodies</b> The models used so far assume that a body is a particle (i.e. has no dimensions) so that all forces acting on it pass through a single point. This is not always satisfactory and a development of the model is to assume that the body has size and is rigid (is not deformed when acted on by a force). The weight of the body is taken to act through a point called the centre of mass.	<ul> <li>E.g. Paul has mass 42 kg , Lewis 40 kg and Clare 30 kg. They are playing on a see-saw.</li> <li>1. Paul sits 2 m from the fulcrum. Where does Lewis need to sit in order to balance the see-saw?</li> </ul>
References: Chapter 3 Pages 27-29 Exercise 3A Q. 2	MomentsIf a force does not act through a point then it has a turning effect - or moment - about that point. The moment of a force about a point is defined as :  Moment = $Fd$ where d is the perpendicular distance of the point from the line of action of the force, F. In two dimensions, mo- ments can be clockwise or anti-clockwise.	$42g \text{ N} \qquad 40g \text{ N}$ $M(O) \text{ a.c.:} 42g \times 2 - 40gx = 0$ $\Rightarrow x = 2.1 \qquad \text{Lewis sits } 2.1 \text{ m from O.}$ 2. Paul sits 2 m from the fulcrum. Lewis sits on the other side, 0.9 m from the fulcrum. Where does Clare have to sit to balance the see-saw? $P \qquad O \qquad L \qquad C$
References: Chapter 3 Page 29	<b>Couples</b> If there is no overall resultant force, then the body will have no linear acceleration. Two forces equal in magni- tude, opposite in direction and acting along parallel but different lines will have a turning effect called a couple.	$42g \text{ N} \qquad 40g \text{ N} \qquad 30g \text{ N}$ $42g \text{ N} \qquad 40g \text{ N} \qquad 30g \text{ N}$ $40g \times 30g \text{ N} \qquad 40g \times 30g \text{ N}$ $40g \times 2 = 0 \Rightarrow 30gx = 48g$ $3 \Rightarrow x = 1.6  \text{Clare sits } 1.6 \text{ m from O.}$
References: Chapter 3 Pages 29-32 Exercise 3A Q. 7 References: Chapter 3	<b>Equilibrium</b> When all the forces on a body act through a point, the body is in equilibrium if there is zero resultant force. When the forces do not all act through the same point, the body is in equilibrium only if the total moment about every point is also zero. When the resultant force is zero, if the moment of all the forces about any one point is zero then it will also be zero about every other point.	E.g. A bar of length 40 cm and weight 30 N is supported horizontally by two supports, 10 cm from reach end. The centre of mass of the bar is 18 cm from the left-hand end. Find the reaction forces on the supports. $R_1 N = \frac{R_2 N}{10 \text{ cm} + 8 \text{ cm} + 12} = 10$
Page 40-45 Exercise 3B Q. 1, 7	<b>Moment of a forces at angles</b> When <i>d</i> is the distance from a point A to some point B on the line of action of the force <i>F</i> such that AB makes an angle of $\theta$ with F, the moment of <i>F</i> about A is $Fx = Fd\sin\theta$ .	$R(\uparrow): R_1 + R_2 = 30$ $M(D) \text{ c.w.: } 20R_1 - 12 \times 30 = 0$ $\Rightarrow R_1 = 18 \text{ and } R_2 = 12$ E.g. A uniform bar AC of mass 12 kg and
References:	Note that this is equivalent to considering the moments about A of the resultant parts of <i>F</i> in directions parallel and perpendicular to AB.	length 80 cm is freely hinged on a wall. It is held horizontally by a wire fixed to the wall 60 cm above the hinge. Find the tension in the wire.
Chapter 3 Pages 53-55 Exercise 3C	<ul> <li>Two surfaces slide when the limiting frictional force is insufficient to maintain equilibrium.</li> <li>(*) The resultant normal reaction, <i>N</i>, between two surfaces must pass through a point of contact of the surfaces.</li> </ul>	$M(A) c.w.: 40 \times 12g - Td = 0$ $d = 80 \times \sin \alpha = 48$ $\Rightarrow 48T = 480g$ $\Rightarrow T = 98$ The tension is 98 N. Lengths in cm $Mechanics 2$
Q. 2, 5	reached while the condition (*) holds, sliding takes place first. If not the body topples first.	Version B: page 3 Competence statements d 5, 6, 7, 8, 9 © MEI



References: Chapter Pages 143-

> Example Page 14

Exercise

eferences: Thapter 7 es 143-147	<b>Frameworks</b> A framework is an arrangement of rods or struts hinged (or "pin-jointed") at the ends of the rods.	E.g. The framework ABC as shown is in a vert plane and is made up of three light rods freely jointed at A, B and C. A mass of 10 kg is hung from C. Taking $g = 10 \text{ m s}^{-2}$ , find the normal reactions at A and B. Find also the forces in the
ample 7.2 Page 146	<ul> <li>Simplifying assumptions <ol> <li>All parts of the framework are light.</li> <li>All the pin-joints are smooth.</li> <li>Any loads or other external forces are attached at the pin-joints.</li> </ol> </li> <li>The result of these assumptions is that all internal forces are directed along the rods. The forces are tension or thrust (compression).</li> <li>Tension Thrust</li> </ul> Method of solution <ol> <li>Label all the internal forces. They may be marked as tensions or thrusts but you may find it better to mark them all as tensions; any negative values will be thrusts.</li> <li>By resolving and taking moments, as far as possible calculate the external forces on whole system.</li> <li>Take each pin-joint in isolation and find horizontal and vertical equilibrium equations for all the forces ato a minimum at each stage.</li> <li>When up-dating your diagram, remember keep the sign of each force relative to the direction marked. </li> <li>In general there will be a redundant point i.e. to find all the forces it will be necessary to work at all but one of the pin-joints. The values already found may be checked for this point.</li> </ol>	and determine whether they are in tension or in thrust. $R_{1} N = 16 \text{ cm} = 10^{\circ} \text{ m} $

E.g. The framework ABC as shown is in a vertical rods freely pin-0 kg is hung the normal forces in the rods tension or in



and B,  $R_1$  N and s  $90^{\circ}$  because

### Summary M2 Topic 2: Work, Energy and Power



8 m

References: Chapter 5 Pages 87-94 Exercise 5A Q. 1(i), 2(ii), 4	Energy and Work The energy of an object is changed when it is acted on by an unbalanced force. When a force moves an object, the force is said to do work. Work done = force × distance moved in direction of force	<ol> <li>Examples         <ol> <li>Work done by a force of 200 N in moving an object 3 m = 600 Joules.</li> <li>A body increases speed due to a force of 30 N acting for 3 m. Kinetic Energy gained = 30x3 = 90 J</li> <li>If the body above has mass 4 kg and was at rest</li> </ol> </li> </ol>
	The SI unit of work is the joule, J (N m). Kinetic energy is energy possessed because of motion. For the linear motion of a body of mass <i>m</i> and speed <i>v</i> . Kinetic Energy $=\frac{1}{2}mv^2$ The work-energy principle Work done by resultant force = increase in kinetic energy of object	then Kinetic Energy = $\frac{1}{2} \times 4 \times v^2 - 0 = 90$ $\Rightarrow v = \sqrt{45}$ . Final speed is 6.71 ms <sup>-1</sup> (3 s. f.) 4. A car of 1.5 tonnes is brought to rest in 100 m from a speed of 30 m s <sup>-1</sup> by the brakes exerting a constant force. Find the force. Work done = Final K.E. – Initial K.E. $\Rightarrow 100F = \frac{1}{2} \times 1500 \times 30^2 - 0$
References: Chapter 5 Pages 96-100	Potential EnergyPotential energy is energy stored because of position. In this unit it is the work done against gravity when an object is raised and the work done by gravity when it is lowered.P.E. = $mgh$	$\Rightarrow F = \frac{15 \times 900}{2} = 6750.$ Force is 6750 N <b>Examples</b> 1. A sledge carrying a child, with a total mass of 50 kg, slides from rest down a smooth snow slope of length 20 m. The slope drops 8 m vertically
References: Chapter 5 Page 97	<b>Conservation of mechanical energy</b> When gravity is the only force which does work, mechanical energy is conserved and Kinetic energy + Potential energy = constant	Find the speed at the bottom of the slope. F = 0, u = 0  and  h = 8. $\frac{1}{2}mv^2 - \frac{1}{2}mu^2 = mgh$
References: Chapter 5 Pages 101-102	Work and kinetic energy for 2-dimensional motion A force acting at right angles to the direction of motion does no work. If a force is acting at an angle to the direction of	$\Rightarrow \frac{1}{2}mv^2 = 8mg \Rightarrow v^2 = 16g$ $\Rightarrow v \approx 12.5 \text{ m s}^{-1}.$ 8  m 50g
Exercise 5B Q. 8	motion then resolve into two forces, along the direction of motion and perpendicular to it. NB The work done is calculated as <b>either</b> force $\times$ dist moved in direction of force <b>or</b> dist moved $\times$ component of force in direction of displacement.	2. The snow slope is not smooth and $\mu = 0.3$ . What now will be the speed at the bottom of the slope? $F = \mu R$ and $R = mg \cos \theta$ $\Rightarrow F = \mu mg \cos \theta$ where $\sin \theta = \frac{8}{20}$ .
References: Chapter 5 Pages 109-111 Exercise 5C Q. 3, 9	<b>Power</b> Power is the rate at which work is done. $P = \frac{Fs}{t} = Fv$ for a constant force F	$\Rightarrow (mg\sin\theta - \mu mg\cos\theta) \times 20 = \frac{1}{2}mv^2 - 0$ $\Rightarrow 8g - 6g\cos 23.58 = \frac{1}{2}v^2$ $\Rightarrow v^2 \approx 49 \Rightarrow v \approx 7. \text{ Speed } \approx 7 \text{ m s}^{-1}.$
Mechanics 2 Version B: page 5 Competence state © MEI	ments w 1, 2, 3, 4, 5, 6, 7, 8, 9	E.g. A mass of 10 kg is being raised at 2 m s <sup>-1</sup> . What is the power required? $F = 10g$ : power = $10g \times 2 = 20g = 196$ W



References:	Impulse and Momentum	Magnitude of momentum of
Pages 118-123	as Impulse = Force × time	(a) a car of 1.2 tonnes moving at 3 m s $^{-1}$ is 1200 × 3 = 3600 N s,
Exercise 6A Q. 1(i), 2(i)	The <i>linear momentum</i> of a body is defined as <i>m</i> <b>v</b> . (In this unit linear momentum is simply called	(b) a of hockey ball of 0.18 kg moving at $20 \text{ m s}^{-1}$ is $0.18 \times 20 = 3.6 \text{ N s}.$
	A force acting on a body changes its velocity and hence its momentum.	Magnitude of impulse of force of 500 N acting for 2 sec is 1000 N s.
	If a force acts for time $t$ and changes the velocity from <b>u</b> to <b>v</b> , then	A hockey ball of mass 0.18 kg is slowed down by resistance to the ground from $20 \text{ m s}^{-1}$ to $10 \text{ m s}^{-1}$ in 4 seconds.
	Impulse = final momentum – initial momentum $\mathbf{J} = \mathbf{F}t = m\mathbf{v} - m\mathbf{u}.$	Take $J$ , the impulse and $F$ , the friction, to be in the direction of motion:
Exercise 6A Q. 8, 10	Impulse and momentum are both vector quanti- ties.	$J = 0.18 \times 10 - 0.18 \times 20 = -1.8$ Now $4F = -1.8 \Rightarrow F = -0.45$ N. Resistance opposes motion with a force of 0.45 N.
	The impulse of a variable force is given by	
	$\int_{0}^{T} \mathbf{F} dt = m\mathbf{v} - m\mathbf{u}$	E.g. The direction of a hockey ball of 0.18 kg is changed by a force acting for 1.2 sec. The original velocity was $(12\mathbf{i} + 13\mathbf{j})$ m s <sup>-1</sup> and the final
References: Chapter 6	The units of momentum and impulse are the N s.	velocity is $(24\mathbf{i} + 5\mathbf{j}) \text{ m s}^{-1}$ . Find the magnitude, <i>F</i> N, of the force.
Pages 128-134	<b>Conservation of momentum</b>	1.2 $\mathbf{F} = 0.18((24\mathbf{i} + 5\mathbf{j}) - (12\mathbf{i} + 13\mathbf{j})) = 0.18(12\mathbf{i} - 8\mathbf{j})$
Exercise 6B	momentum of the system is conserved.	$\Rightarrow \mathbf{F} = 1.8\mathbf{i} - 1.2\mathbf{j}$ $\Rightarrow  \mathbf{F}  = \sqrt{1.8^2 + 1.2^2} = 2.16 \text{ N} (3.8 \text{ f})$
Q. 2	$m_{\rm A}\mathbf{v}_{\rm A}+m_{\rm B}\mathbf{v}_{\rm B}=m_{\rm A}\mathbf{u}_{\rm A}+m_{\rm B}\mathbf{u}_{\rm B}$	
References: Chapter 6 Pages 138-142	<b>Coefficient of restitution</b> Newton's Experimental Law (Law of Impact) for direct impact:	1. A railway truck of mass 25 tonnes is moving along a horizontal track at 7 m s <sup><math>-1</math></sup> when it collides with a stationary truck of mass 10 tonnes. They join and move on along the track together. With
	Before $u_A$ $u_B$	Momentum is conserved so:
Exercise 6C		$35v = 25 \times 7 + 10 \times 0 \Longrightarrow v = 5$
Q. 5	After $v_{\rm A}$ $v_{\rm B}$	$\Rightarrow$ speed is 5 m s <sup>-1</sup> .
	$\frac{\text{speed of separation}}{\text{speed of approach}} = \text{constant.}$	(Notice that the units of mass are unimportant so long as they are consistent.)
	We write $\frac{v_{\rm B} - v_{\rm A}}{u_{\rm D} - u_{\rm A}} = -e.$	2. If it is the lighter truck that is moving at 7 m s <sup><math>-1</math></sup>
	The constant, $e$ , is called the coefficient of restitution.	and it collides with the heavier truck which is sta- tionary, then with what speed do they move?
	For all pairs of surfaces, $0 \le e \le 1$	$35v = 10 \times 7 + 25 \times 0 \implies v = 2$
References: Chapter 6	<b>Direct impact with a fixed surface</b> The speed of the fixed surface before and after the	$\Rightarrow$ speed is 2 m s <sup>-1</sup> .
Page 139	impact is 0.	Mechanics 2
Exercise 6C Q. 3	i.e. $v = eu$ . $u \downarrow \bigcirc \uparrow_v$	© MEI



E.g. Two balls of mass *m* moving in opposite References: **Direct collision in a straight line** directions at 2 m s<sup>-1</sup> and 1m s<sup>-1</sup> hit each other Chapter 6 See diagram on previous sheet. directly. The coefficient of restitution is 0.5. Page 131 By Newton's experimental law  $\frac{v_{\rm B}-v_{\rm A}}{u_{\rm B}-u_{\rm A}}=-e.$ Before e = 0.5Example 6.10 Page 131 If A catches up with B then  $u_A > u_B$  but after the After collision  $v_{\rm B} > v_{\rm A}$ . N.E.L:  $v_2 - v_1 = -0.5(-1-2) = 1.5$ By conservation of momentum Exercise 6C Cons. of momentum:  $mv_2 + mv_1 = 2m + (-1)m$ Q. 9  $m_{\rm A}v_{\rm A} + m_{\rm B}v_{\rm B} = m_{\rm A}u_{\rm A} + m_{\rm B}u_{\rm B}$  $\Rightarrow v_2 + v_1 = 1$ Solving simultaneously:  $v_1 = -0.25$ ,  $v_2 = 1.25$ Given sufficient information, the two equations The directions of motion are reversed and the may be solved simultaneously. second ball now moves faster. References: **Oblique Impact with a smooth plane** If, in the case of the two trucks (see previous page), Chapter 6 When an object hits a smooth plane there can be no the coefficient of restitution between the two trucks Pages 137-139 impulse parallel to the plane so velocity is is 0.5 then find the velocities in the two cases above unchanged in this direction. after the collision. Newton's experimental law (NEL) applies to the Exercise 6D 1. before  $7ms^{-1}$   $0ms^{-1}$   $\rightarrow$   $\rightarrow$  25t 10t e = 0.5  $\rightarrow$   $\rightarrow$ after  $v_1 ms^{-1}$   $v_2 ms^{-1}$ components of velocity in the direction Q. 5, 10 perpendicular to the plane. When a ball is travelling with speed *u* at an angle of  $\alpha$  to the plane: (as before)  $25v_1 + 10v_2 = 25 \times 7 + 10 \times 0$  (Cons. of mom.) Original velocity perp. to the plane =  $u\sin\alpha$ Final velocity perp. to the plane =  $ue\sin\alpha$  $v_2 - v_1 = -0.5(0 - 7) = 3.5$  (NEL)) Original velocity parallel to the plane =  $u\cos\alpha$ so  $25v_1 + 10v_2 = 175$ Final velocity parallel to the plane  $=u\cos\alpha$ and  $v_2 - v_1 = 3.5$  $\Rightarrow$  v<sub>2</sub> = 7.5, v<sub>1</sub> = 4 after before 2. Before  $0 \text{ m s}^{-1}$   $7 \text{ m s}^{-1}$  $25v_1 + 10v_2 = 25 \times 0 - 10 \times 7$  $v_2 - v_1 = -0.5(-7 - 0) = 3.5$ usina  $\nu \sin \beta = e \mu \sin \alpha$  $\Rightarrow$  v<sub>1</sub> = -3, v<sub>2</sub> = 0.5 (The lighter truck rebounds.) In the second case:  $u\cos \alpha$  $\mathcal{V}\cos\beta = \mathcal{U}\cos\alpha$ . Impulse on 10000 kg truck = 10 000 (0.5–(–7)) Ns If angle of incidence =  $\alpha$ , angle of reflection = $\beta$ = 75000 Ns towards the right.  $\tan\beta = \frac{ue\sin\alpha}{u\sin\alpha} = e\tan\alpha \Longrightarrow e = \frac{\tan\beta}{\tan\alpha}$ K.E. lost on impact  $=\frac{1}{2} \times 25000 \left(0^2 - 3^2\right) + \frac{1}{2} \times 10000 \times (7^2 - 0.5^2)$ Impulse = Final momentum - initial momentum Since the velocity parallel to the plane is  $=131250 \text{ J} \approx 1.31 \text{ KJ} (3 \text{ s. f.}).$ unchanged the momentum in this direction is unchanged and so Impulse = 0. E.g. a ball is moving at 3 m s<sup>-1</sup> and bounces off a smooth wall. The angle of incidence is  $40^0$  and the Perpendicular to the plane the impulse is coefficient of restitution is 0.7.  $meusin\alpha - (-usin\alpha) = (1+e)musin\alpha$ Find the speed after the bounce and the angle of reflection.  $\tan\beta = e\tan\alpha \implies \tan\beta = 0.7 \times \tan 40 = 0.5874$  $\Rightarrow \beta = 30.4^{\circ}$ .  $v = \sqrt{(3\cos 40)^2 + (3 \times 0.7 \times \sin 40)^2} = 2.67$ Mechanics 2 Version B: page 7 The angle of reflection is  $30.4^{\circ}$ Competence statements i 10, 11, 12, 13, 14

and the new speed is  $2.67 \text{ m s}^{-1}$  (3 s.f.).

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## Summary M2 Topic 4: Centre of Mass



References: Chapter 4 Pages 63-67 Example 4.3 Page 66	<b>Centre of mass (c. m.)</b> This is the point through which the weight of the whole body may be considered to act. For the particle model this is the point through which all the forces on the body act. For the rigid body model, the centre of mass is the 'balance point'. For particles on the <i>x</i> -axis, the position, $\overline{x}$ , of the centre of mass relative to a point O is such that the moment of the total mass about the point O is equal to the sum of the moments of the separate masses about O.	E.g. A light rod has masses attached as shown. Find the centre of mass. B A $2 \text{ kg } 4 \text{ kg } 2 \text{ kg } 4 \text{ kg}$ 2  m  2  m  2  m  2  m Total mass = 12 If centre of mass is at $\overline{x}$ from A, then $12\overline{x} = 2 \times 2 + 4 \times 4 + 2 \times 6 + 4 \times 8$ $\Rightarrow 12\overline{x} = 64$ - 16
Q. 2, 4	$\frac{\prod_{i=1}^{n} m_i}{\prod_{i=1}^{n} m_i} x - \sum_{i=1}^{n} m_i x_i$ Uniform bodies	$\Rightarrow x = \frac{1}{3}$ Centre of mass for some shapes
	A uniform body is one made from identical material throughout. It follows that the centre of mass will be at a point of symmetry, if there is one. e.g. a rectangular sheet with constant thickness and density will have its centre of mass where its diagonals intersect.	Solid cone or pyramid $\frac{1}{4}h$ from base.Hollow cone or pyramid $\frac{1}{3}h$ from base.Solid hemisphere $\frac{3}{8}r$ from base.
Exercise 4A Q. 6, 8	<b>Laminas</b> A lamina is a layer (or sheet) whose thickness is negligible.	Hollow hemisphere $\frac{1}{2}r$ from base. Semi-circular lamina $\frac{4r}{r}$ from base
References: Chapter 4 Pages 70-72	Centre of mass for two and three- dimensional bodies Suppose a body consists of point masses $m_i$ at points $(x_i, y_i)$ The centre of mass will be at $(\overline{x}, \overline{y})$ where $M\overline{x} = \sum_i m_i x_i, M\overline{y} = \sum_i m_i y_i$ and $M = \sum_i m_i$ .	See the handbook. E.g. Find the centre of mass, referred to the axes in the diagram, of the given uniform lamina, <i>L</i> . $y \uparrow 1$
Exercise 4B Q. 2, 5	Similarly for 3 dimensions. The centre of mass may also be thought of as the mean position vector of the particles 'weighted' by the masses.	$\begin{array}{c} 4 \\ A \\ 3 \\ 3 \\ B \\ \hline \hline$
	<ol> <li>Composite bodies</li> <li>If there is a line of symmetry then the centre of mass will lie on that line.</li> <li>If the body consists of separate parts then the c. m. of the whole body can be calculated from point masses with the masses of the parts at the centres of mass of the parts.</li> </ol>	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
	$M_{B+C} \mathbf{\bar{r}} = M_B \mathbf{\bar{r}}_B + M_C \mathbf{\bar{r}}_C$	© MEI



This topic relates to the former coursework component of this unit and has been retained because of its general importance and interest. There are no competence statements as such, but elements of the ideas of modelling and testing against experimental results will pervade the examination.		E.g. John drops a ball down a stairwell. (1) He notes that it takes 2 seconds to hit the floor. Taking the time as exact and the value of g = 9.8 m s <sup>-2</sup> , find the height of the stairwell.
References: Chapter 2 Pages 14-16	Using an experiment to test a model A model is a mathematical description of a situa- tion in the real world in which assumptions are made to enable the problem to be solved mathe- matically. When a solution is found it has to be checked against reality. If the match is not good then it may be possible to amend (or refine) the model. This process uses the MEI modelling flowchart. (Students should ask their teacher for this.)	$s = \frac{1}{2}gt^{2}$ $\Rightarrow s = \frac{1}{2} \times 9.8 \times 4 = 19.6 \text{ m}$ (2) In fact, the time of 2 seconds is only correct the nearest second. Find the upper and lower bour for s. Maximum $s = \frac{1}{2}g(2.5)^{2} = 30.625 \text{ m}$ Minimum $s = \frac{1}{2}g(1.5)^{2} = 11.025 \text{ m}$
References: Chapter 2 Pages 16-17	Variation in measurements When a model is tested with an experiment, measurements will be taken. Because of error in measurement and/or variability in the situation there will be some variation in these measure- ments. This variation may be random or system- atic. Consequently, if the experiment is repeatable, a number of measurements should be taken and the mean value found. The maximum and minimum values should be used to estimate the error bounds.	N.B. given this variation in the timing of t note that the value of s found cannot even be given to 1 signifi- cant figure. (3) John uses the experiment to find a value for g. He measures the depth of the drop to be 19.5 m cor- rect to the nearest 0.1m and the time to the nearest second. Find the error bounds for g. $g = \frac{2s}{t^2} \Rightarrow \text{Maximum } g = \frac{39.1}{1.5^2} = 17.4 \text{ (3 s. f.)}$ Minimum $g = \frac{38.9}{t^2} = 6.22 \text{ (3 s. f.)}$
References: Chapter 2 Pages 18-19	<b>Comparing with the model</b> The solution for the model will give a set of pre- dicted results. These values have to be compared with experimental values, and this is often done most conveniently using graphs.	$2.5^2$ i.e. $6.22 < g < 17.4$ E.g. The length and breadth of a rectangular room are measured as 3 m by 4 m, each to the nearest 10 cm. Find the error bounds for the perimeter and area
References: Chapter 2 Pages 20-21 Example 2.1 Page 20	<b>Errors related to significant figures</b> <b>and decimal places</b> Care has to be taken with the precision of meas- urements and also the values assumed to be con- stant. e.g. masses assumed to be as stated by the makers or taking $g = 9.8$ m s <sup>-2</sup> .	Find the error bounds for the perimeter and area. Greatest perimeter = $2(3.05 + 4.05) = 14.2 \text{ m}$ Least perimeter = $2(2.95 + 3.95) = 13.8 \text{ m}$ i.e. perimeter is $14\text{m} \pm 20 \text{ cm}$ greatest area = $3.05 \times 4.05 = 12.3525 \text{ m}^2$ Least area = $2.95 \times 3.95 = 11.6525 \text{ m}^2$ i.e. $11.65\text{m}^2 < Area < 12.35 \text{ m}^2 (3 \text{ s. f.})$
Exercise 2A Q. 1	It may be that the predictions from the model would remain consistent with increased precision in the measurements made.	E.g. Jane measures a stick to be 159 cm when the
References: Chapter 2 Page 21	<b>Percentage error</b> If <i>x</i> is the true value of a measurement and <i>X</i> is the approximated (measured) value then	true length is 160 cm. What is the percentage error? Percentage error = $\frac{100(160 - 159)}{160} = 0.625\%$ Mechanics 2 Version B: page 9 © MEI
Exercise 2A Q. 5, 9	error is given by $\varepsilon$ where $\varepsilon = x - X$ Percentage error $= \frac{100\varepsilon}{x}$	